Material Behaviour

Experimental study on the axial crushing behaviour of pultruded composite tubes

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1. Introduction

A great deal of research and development has been carried out in the past decades to design safer automobiles. Out of the factors considered for safety criteria, the crushworthiness has attracted significant attention due to its multiple functions. The functions of the crushworthiness structures are to (i) absorb energy, (ii) keep the occupant compartments intact and (iii) ensure tolerable deceleration levels for driver and passengers during the crash event. To meet the above functions, the automobile industry is focused on the design architecture and materials used to produce crushworthiness. As a result, different forms of the energy absorbers [1,2] and combinations of high strength metal alloys are used for crushworthiness structures. The focus on new innovative materials which yield superior strength to weight ratio [3] has been increased in order to meet the future stringent crushworthiness norms and to enhance the fuel economy target.

On the other hand, there is a considerable amount of experiments [4–7] conducted on composite material to assess the energy absorption. It is a well-known fact that one can achieve a higher energy absorption compared to metal alloys with the proper construction and architecture of composite structures. Moreover, composites have a relative advantage in terms of the specific energy absorption, ease of manufacture and maintenance. The effect of composite specimen dimensions and its geometry on the energy absorption were studied in refs. [8,9]. However, the energy absorption characteristics are not only depending on the shape of the specimens and its dimensions [5]. Various variables control the energy absorption of the composite structures. The progressive crushing process which yields higher energy absorption depends on the...
mechanical properties of the fibre and the resin, fibre and resin volume fractions, laminate stacking sequence, fibre orientation and the geometry of the tube [5]. To produce a significant deceleration during the crash event, the failed tubes exhibit delamination, bending, axial cracking and fibre fracturing modes [10].

To achieve the above said failure modes and to reduce the peak crush load, an initiator for the stable progressive crushing is very important. Normally these initiators are known as “triggering” mechanisms. Many researchers [5, 8, 9, 11–13] employed edge chamfering of the structures as the triggering mechanism. A few studies have been conducted with square tubes and “I” sectional tubes to study the effect of triggering on energy absorption [14, 15]. However, the effect of triggering mechanisms on the energy absorption of circular tubes is yet to be demonstrated. Mamalis et al. reported [4, 16] that square and rectangular cross sectional tubes have 0.8 and 0.5 times the specific energy absorption of circular specimens. The reason for the lower energy absorption of square rectangular cross sectional tubes is due to the higher stress concentration forming axial cracks only at the corners of the tube. Hence, it is worth investigating the role of different triggering mechanisms on energy absorption of uniform and non-uniform profiles such as circular and square cross section tubes.

A large number of static crushing investigations have been carried out to study the energy absorption characteristics of composite tubes. The advantage of this method is the very slow speed of the crushing process which helps to capture the deformation behaviour of composite tubes. However, most of the practical applications are dynamic in nature. The dynamic study of composite materials needs considerable instrumentation and infrastructure. Hamada et al. [17] reported that the energy absorption of the same composite tube was less in the case of dynamic load compared to static. Farley et al. [18] investigated the effect of strain rate on the energy absorption using carbon–epoxy and aramid–epoxy tubes. They reported that the resin stiffness and failure strain can be a function of strain rate. Hence, the major energy absorption associated with the interlaminar crack growth may be considered as a function of crushing speed. So, the investigation of the effect of strain rate on energy absorption of other fibre and resin types is necessary for high impact loading applications.

Ramakrishna [5] compared the energy absorption characteristics of thermoset (carbon–epoxy) and thermoplastic (carbon–PEEK) matrices. He concluded that the energy absorption of a resin depends on the interlaminar fracture toughness and its failure strain. Polyester resins are widely used in most applications due to their high performance to cost ratio. Vinylester resins are gaining popularity as they have better adhesion and fatigue properties than polyester whilst costing less than epoxy. Moreover, vinylester [19] has higher strain to failure than polyester. Due to above facts, the two resins, polyester and vinylester, were chosen for our study.

Many studies [6, 20] demonstrated that fibre orientation along the axis of the tube absorbed more energy than other orientations. In connection with that, pultruded tubes were chosen for this study. Square tubes made up of glass–polyester and circular tubes with glass–polyester and vinylester were considered for our investigation. The effect of the geometry profile, triggering mechanism, strain rate and the type of resin on the energy absorption was studied experimentally.

2. Materials and experimental methods

2.1. Composite tubes

All the tubes used for the tests were manufactured by a pultrusion process (M/s EXEL, Belgium). The tube laminates were made with continuous 0° orientation fibres. To get a better surface finish, the outer and inner layers were made up of random short glass fibres with approximate thickness of 0.1–0.2 mm. The architectural construction of

![Fig. 1. Architectural construction of the pultruded tubes.](image1)

![Fig. 2. Circular tube (a) Triggering type 1 (b) Triggering type 2.](image2)
the circular pultruded profiles used for our study is schematically shown in Fig. 1. Six different tube combinations SP1, SP2, CP1, CP2, CV1 and CV2 were studied experimentally. SP1 refers to the square cross sectional glass–polyester pultruded tube with triggering type 1. SP2 refers to the square cross sectional glass–polyester pultruded tube with triggering type 2. CP1 and CP2 refer to the circular cross sectional glass–polyester tube with triggering type 1 and 2 respectively. Similarly, CV1 and CV2 refer to the circular cross sectional glass–vinylester tube with triggering type 1 and 2 respectively. The triggering type 1 is 45° chamfering around the edges of the tubes, and the type 2 is a tulip pattern with an included angle of 60° between the edges. The details of the two triggering profiles for circular tubes are shown in Fig. 2. The motivation to choose these types was: for type 1 profile the initial contact of the impactor will be uniform along the circumference of the tube at the time of impact, whereas in the case of type 2 the contact will take place at the sharp edges of the specimen. The first mechanism would enhance uniform circumferential interlaminar cracks causing uniform delamination, whereas, in the case of triggering type 2, the initial cracks develop at the sharp edges of the tube which make first contact with the impactor. The circular and square test specimens with two types of triggering are shown in Fig. 3.

Studies conducted on the progressive crushing of circular cross-sectional tubes proved that tubes having a \( t/D \) ratio less than 0.015 will fail catastrophically (\( t \) – thickness of the tube; \( D \) – diameter of the tube) [21]. However, tubes with a \( t/D \) ratio in the range of 0.015–0.25 will crush progressively. So, the \( t/D \) ratio of the circular tubes was chosen as 0.06 and 0.07 for CP and CV series respectively. For SP series, a \( t/W \) ratio of 0.075 (\( W \) – width of the tube) was chosen. The tolerances in the tube dimensions (outer width, outer diameter and thickness) were checked. The standard deviation of outer width and thickness of SP series and outer diameter and thickness of CP and CV series were 0.05, 0.05; 0.09, 0.12; 0.05 mm and 0.04 mm respectively.

To achieve the progressive failure of the composite tubes, the linear density (mass per unit length) of the tube was chosen as recommended in ref. [22]. The resin and the fibre volume fraction were calculated based on ASTM D 2584. The details of the tube geometry, fibre, resin, tube dimensions, linear density and the corresponding volume fraction are mentioned in Tables 1 and 2.

### 2.2. Experimental set-up

All tests have been performed with the large-scale drop weight test facility shown in Figs. 4 and 5. The main horizontal supporting structure is attached to a vertical wall. The horizontal supporting structure carries the vertical guides along which the impactor slides. An impactor mass of 68.85 kg was used for all tests. The bottom surface of the impactor was made flat to affix the composite test specimen and to ensure a co-axial condition between the test specimen and the impactor (Fig. 5). A scale was fixed parallel to the guiding rail to measure the drop height. The maximum drop height of the experimental setup is 12 m. However, for this experiment the impact height was limited to 10 m. The bottom of the vertical sliding support is fixed to a 20 mm thick steel plate to withstand the total impact force during the impact test. The impact base plate setup was placed over a massive concrete base.

<table>
<thead>
<tr>
<th>S.No</th>
<th>Tube series</th>
<th>Cross section</th>
<th>Fibre</th>
<th>Resin</th>
<th>Dimensions (mm)</th>
<th>Linear (g/mm)</th>
<th>Volume fraction</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>SP</td>
<td>Square</td>
<td>Glass</td>
<td>Polyester</td>
<td>Outer width = 60</td>
<td>1.81</td>
<td>Resin ( (V_r) ) = 49.2%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Thickness = 4.5</td>
<td></td>
<td>Fibre ( (V_f) ) = 50.8%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Length = 220</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2.</td>
<td>CP</td>
<td>Circular</td>
<td>Glass</td>
<td>Polyester</td>
<td>Outer diameter = 50</td>
<td>0.66</td>
<td>Resin ( (V_r) ) = 51.7%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Thickness = 3</td>
<td></td>
<td>Fibre ( (V_f) ) = 48.3%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Length = 220</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3.</td>
<td>CV</td>
<td>Circular</td>
<td>Glass</td>
<td>Vinylester</td>
<td>Outer diameter = 38</td>
<td>0.60</td>
<td>Resin ( (V_r) ) = 49.7%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Thickness = 3</td>
<td></td>
<td>Fibre ( (V_f) ) = 50.4%</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Length = 220</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
2.3. Data acquisition system

The system was equipped with a high-speed camera (Photron APX RS 250K) with maximum frame rate of 250,000 fps (Fig. 6); this was connected to a computer which records the images at specified times during the impact event. The tracking area by the camera covered the entire impact base. A special metal – halide lamp was used to maintain the light intensity at the area of impact.

To capture the crash event of the composite tubes, a frame rate of 2000 fps was chosen. The corresponding pixel resolution of the screen was $1024 \times 1024$, with a remaining resolution of $384 \times 400$ for the area of impact. Markers were placed on the impactor as well as on the test specimen for digital image tracking. About half a meter height from the base of the impact system was covered by the lens of the high-speed camera. The position of the impactor was recorded at every instance of impact time. From these data, the corresponding velocities were calculated. Due to the clearance between the impactor guiding system and the impactor, a small change in the horizontal velocity was noticed. However, compared to the magnitude of the vertical velocity it was negligible.

<table>
<thead>
<tr>
<th>S.No</th>
<th>Tube series</th>
<th>Total volume fraction of fibre</th>
<th>Volume fraction of 0(^\circ) lay-up</th>
<th>Volume fraction of random mat</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.</td>
<td>SP</td>
<td>50.8%</td>
<td>40.3%</td>
<td>10.5%</td>
</tr>
<tr>
<td>2.</td>
<td>CP</td>
<td>48.3%</td>
<td>36.2%</td>
<td>12.1%</td>
</tr>
<tr>
<td>3.</td>
<td>CV</td>
<td>50.4%</td>
<td>41.4%</td>
<td>9.0%</td>
</tr>
</tbody>
</table>

2.4. Data processing using digital image correlation technique

Traditionally, many contact sensors have been employed to collect the data during an impact test. Often, to select the appropriate data acquisition equipment, prior knowledge of the magnitude of the peak crushing force and the duration of the crash event is important. However, this is not an easy task. Any improper selection would lead to loss of sensors and equipment. Hence, a contact-less method is an interesting alternative to collect the data during such high dynamic events. In this paper, the digital
image correlation technique is used to measure the impact velocity and the corresponding impact force. From the data obtained from the high-speed images, the deformation length of the tube (equivalent to the displacement of the impactor) with respect to time was calculated using the digital image correlation commercial code Vic-2D. Subsequently, the above data was differentiated to get the impact velocity and the corresponding deceleration of the impactor for every time interval. It was assumed that the deceleration of the impactor was constant during a time interval. Based on this assumption, the reaction force of the tube was calculated by the multiplication of the mass of the impactor and the deceleration during the time interval [23]. Further details for this method (DIC) of calculation can be found in ref. [24].

3. Experimental results and discussions

3.1. Failure pattern

The progressive failure pattern of different types of composite tubes was investigated with different impact velocities. Each set of composite tubes consists of square (SP1 and SP2) and circular tubes (CP1, CP2, CV1 and CV2). They were tested with different drop heights which correspond to 9.3, 12.4 and 14 m/s initial impact velocities. Different phases of deformation of a circular composite tube are shown in Fig 7. All the tubes exhibited the progressive crushing failure modes.

3.1.1. Square tubes

For both types of square tubes (SP1 and SP2), after the circumferential delamination due to stress concentration, primary longitudinal cracks were developed along the corners. As a result, each side of the tube has split into petals moving inwards and outwards. The major impact energy of both types of tubes was exhibited by lamina bending followed by the breakage of resin bonds. The separation of plies was directly proportional to the number of interlaminar cracks which developed during the impact process. The complete surface delamination of inner and outer random fibre mat was observed from the core fibres. The de-cohesion of outer and inner skin is due to the uneven distribution of the bonding strength along the thickness of the tube. The lamina of each face of the square tube acted as a cantilever beam, which absorbed a considerable amount of energy by its bending mode. During the crash event, the bending angle of each petal was observed 90° for all square tubes. However, due to the high stiffness of each petal the angle was gradually reduced when the impact force magnitude approached zero (Fig. 8(a) and (b)). This mode was observed to be different from the previously reported modes [25] where all the petals deformed permanently for 90°. However, the inner laminas have undergone permanent bending as well as tearing mode (Fig. 8(a) and (b)). Unlike triggering type 1, triggering type 2 exhibited permanent bending of the laminas due to their lower stiffness. This can be clearly seen in Fig. 9(a) and (b).
3.1.2. Circular tubes

Similar to square tubes, in all varieties of circular tubes (CP1, CP2, CV1 and CV2) the inner and outer petals were formed due to the circumferential delamination and, consequently, axial cracks were formed parallel to the axis of the tube. The uniform geometry of the circular tube facilitated to form more axial cracks and, thus, more petals were formed. The major amount of impact energy was absorbed due to the increasing number of longitudinal cracks and subsequent bending of the laminates [10]. This phenomenon was clear in all cases in which the specific energy absorption of the circular tube was more than the square tube. Unlike the square tubes, irrespective of the triggering and fibre volume fraction, the bending angles of the laminates were greater than or equal to 90° (Figs. 10 and 11). For all tube series (SP1, SP2, CP1, CP2, CV1 and CV2), the bending of the inner petals reduced the acceleration of the impactor considerably due to the blockage of material within the profile.

3.1.3. Study of longitudinal cuts

After the impact testing, all samples were longitudinally cut to carry out a visual inspection of the crushed zone. The cut section of all tube series gave clear evidence that the major delamination took place at the mid thickness of the tube. A similar result was reported in refs. [10,26]. Other than the axial cracks, a smaller number of trans-laminar cracks (cracks which are perpendicular to the direction of the fibre orientation) were noticed for the SP series. These axial and trans-laminar cracks were longer in length. In contrast, for CP and CV series, a larger number of axial and trans-laminar cracks were observed, however the length of the axial and trans-laminar cracks were controlled by the uniform geometry of the circular tubes. As a result, each laminate has split into a larger number of thinner layers. Due to the controlled axial trans-laminar cracks, more fibres of the CP and CV series have undergone fracture at the fixed end of the cantilever portion. In the case of SP series, less fibres had undergone fracturing due to the larger radius of bending. This phenomenon can be clearly seen from the difference between the amount of fibres and their angle of bending between square and circular tubes (Figs. 12 and 13). Unlike SP and CP series, in the case of CV series there was no de-cohesion of the random mat from the core fibres noticed. The better adhesion property of vinylester resin attributed to the increasing uniform strength along the thickness of the tube.
3.2. Force-deformation curves

The force-deformation curves of the tube series SP1, CP1 and CV1 for different initial impact velocities are shown in Figs. 14–16. In all series, the force-deformation curves followed three phases. The first phase was the sudden increase in peak load at the initial stage of compression. During this stage, the triggering length of the tube was completely crushed and was followed by the start of the circumferential delamination. The area under the peak load in the force-deformation curve corresponds to the total energy spent on the initial circumferential delamination of the composite tube. After the circumferential delamination, the peak load decreased abruptly. This corresponds to the second stage of the crushing. At the end of this second stage a significant amount of energy was consumed by bending of the petals followed by the shear deformation of plies that led to fibre fracture at the fixed end of the petal. The chronological order of delamination, axial cracks, bending of petals and, due to that, the shear fracture of the fibre continued for the subsequent stages of crushing. Due to the above failure modes, the crushing load of the tube oscillated around a mean value. This was the third stage of crushing. The similar trend of all three stages was also observed in the case of triggering type 2. However, due to the triggering tulips, the time to reach the major delamination was different than for type 1 series and a smaller slope of the peak load was observed. The magnitude of the peak crushing load and the corresponding mean crushing load are given in Table 3. The mean crushing load of all tube series was calculated based on Equation (1).

\[
P_{\text{mean}} = \frac{\int_{0}^{l_{\text{max}}} P(l)dl}{l_{\text{max}}} \quad (\text{kN})
\]

where \( P(l) \) is the instantaneous crushing load corresponding to the instantaneous crushing deformation length dl. \( l_{\text{max}} \) is the maximum or total deformation length. The ratio of the mean crush load to the peak crush load, which indicates the efficiency of the crushing (\( \eta_c \)), is also given in Table 3. In the case of the SP1 and CP1 series, the tests at three different velocities (9.3, 12.4 and 14 m/s) exhibited a very similar peak crushing load. However, in the case of the CV1 series, a minor increase in peak load was observed with increasing impact velocity. The CP1 and CV1 series exhibited approximately the same mean crush load for all three-impact velocities. As a result, the crush efficiency of these tube series remained approximately constant for all

Fig. 11. (a) and (b): Failure patterns of CV1 and CV2 series.

Fig. 12. (a) Longitudinal cut section of SP1 tube (b) Longitudinal cut section of SP2 tube.
impact velocities. In the case of SP1, the mean load of crushing was increased with increasing impact velocity and, consequently, the crush efficiency was also increased. The increased mean crush load may be due to the blockage of the material at the inner profile of the tube.

3.2.1. Effect of triggering on peak load

The effect of triggering on the load-deformation curve for the tube series SP, CP and CV can be clearly seen from Figs. 17 to 19. For SP and CV tube series, no appreciable difference in peak load was noticed between triggering type 1 and 2. However, in the case of the CP series, due to the triggering type 2, there was a 12% reduction in peak load. In all tube series with triggering type 2, the average slope to reach the peak load was uniform. The gradual increase in the load was due to the reduced stiffness of each tulip and, hence, less energy was required for delamination. However, in both cases the peak load occurred at a stage where the circumferential delamination took place. For the CP and CV series, a higher deformation length was seen due to triggering type 2. However, in the case of the SP series there was a negative effect observed and so the deformation length of triggering 1 was higher than type 2. Apart from the peak load, a significant difference in the mean crush load was noted for triggering type 2 series. Apart from the SP tube series, the mean crush load of CP2 and CV2 were smaller than CP1 and CV1. The lower mean crush load of the tube series may be due to the delayed major delamination and, subsequently, less resistance offered by the triggering tulips. The comparison of peak and mean crush load of all tube series for the initial impact velocity 9.3 m/s is given in Table 3.

3.3. Specific energy absorption

In order to determine the deformation length of the tube series, two specimens were tested in each category. The maximum deformations of the tubes were taken into account and, thus, minimum specific energy absorption of each case was calculated. The total energy absorption \( E_d \) of each case was calculated based on Equation (2) and the same is summarized in Table 3.

\[
E_d = \int_0^{l_{\text{max}}} P(l) \, dl
\]  

(2)

To understand the energy absorption effectiveness of each tube, the specific energy absorption (SEA –
normalized with respect to mass) was calculated based on Equation (3).

\[
\text{SEA} = \frac{\int_0^{l_{\text{max}}} p(l)dl}{l_{\text{max}}r} \left( \frac{1}{\rho} \right) \text{(kJ/kg)}
\]

where \( \rho \) is the linear density of the composite tube (kg/m).

### 3.3.1. Effect of geometry and triggering on SEA

The comparison of the specific energy absorption of the SP, CP, and CV series of triggering type 1 and 2 for the initial impact velocity 9.3 m/s is presented in Fig. 20. The specific energy absorption of circular tubes (CP and CV series) in all cases is higher than the square tubes (SP series). As discussed earlier in Section 3.1.2, the uniform geometry the circular tube yielded a larger number of axial cracks. These cracks attributed to a higher specific energy absorption. In case of square tubes, due to the higher stress concentration, the major axial cracks were formed at the four corners of the tube. Out of the total energy absorbed by the square tube in each category (SP1 and SP2), a significant amount of energy was absorbed by lamina bending followed by shear fracture at the fixed end of each sub-laminate.

The effect of triggering on SEA is also clearly explained by Fig. 20. In the case of CP and CV series, triggering type 1 absorbed more energy than triggering type 2. This is due to the fact that, during the impact event, the controlled circumferential delamination followed by the axial cracks took place uniformly along the circumference of the tube. In the case of triggering type 2, the delamination propagated at the sharp edges of the tube. The crushing of the triggering length of the tube delayed the major circumferential delamination. Compared to triggering type 1, an approximate time delay of 2–3 ms was observed in all cases of triggering type 2. This can be noted from the shift of peak load compared to type 1 in Figs. 17–19.

Due to the above effects, the SEA of CP2 and CV2 series are 7.4 and 9.8% lower than CP1 and CV1 series for the case with initial impact velocity 9.3 m/s. However, in the case of square tubes the SEA was higher for triggering type 2 than for triggering type 1. An increase in SEA of 16.5% was seen for SP2 tubes compared to SP1 tubes. Although the delay in delamination occurred between triggering type 1 and 2, in both SP1 and SP2 series a significant amount of energy was dissipated by lamina bending followed by the shear fracturing of the fibres. The stiffness of each side of the laminate SP2 tubes was less than SP1 series. The lower stiffness of each laminate was attributed to the shear fracture of fibres at the base of the tulips followed by the major delamination. Due to this effect, each laminate of SP2 series exhibited a permanent bending angle of 90°, whereas in the case of triggering type 1 it was approximately 45°.

### 3.3.2. Effect of strain rate and resin type on SEA

The initial study of the tubes for the impact velocity 9.3 m/s indicated that the specific energy absorption of tube series CP1 and CV1 exhibited more SEA than type 2. The results for impact velocities 12.4 and 14 m/s are shown in Table 3.

<table>
<thead>
<tr>
<th>Tube series</th>
<th>Impact velocity 9.3 m/s</th>
<th></th>
<th>Impact velocity 12.4 m/s</th>
<th></th>
<th>Impact velocity 14 m/s</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Peak load (kN)</td>
<td>Mean load (kN)</td>
<td>Absorbed energy (kJ)</td>
<td>( \eta_c ) (%)</td>
<td>Peak load (kN)</td>
</tr>
<tr>
<td>SP1</td>
<td>73</td>
<td>31.01</td>
<td>2.563</td>
<td>42.5</td>
<td>77</td>
</tr>
<tr>
<td>SP2</td>
<td>73</td>
<td>37.20</td>
<td>2.680</td>
<td>51.9</td>
<td>–</td>
</tr>
<tr>
<td>CP1</td>
<td>78</td>
<td>28.34</td>
<td>3.462</td>
<td>36.4</td>
<td>76</td>
</tr>
<tr>
<td>CP2</td>
<td>69</td>
<td>26.05</td>
<td>3.470</td>
<td>37.8</td>
<td>–</td>
</tr>
<tr>
<td>CV1</td>
<td>59</td>
<td>38.66</td>
<td>2.938</td>
<td>65.5</td>
<td>60</td>
</tr>
<tr>
<td>CV2</td>
<td>63</td>
<td>34.62</td>
<td>3.448</td>
<td>55.3</td>
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</tr>
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</table>

Fig. 16. Force-deformation curves for CV1 series.

Fig. 17. Comparison of SP1 and SP2 tubes.

Table 3
Summary of crushing loads and absorbed energy.
Therefore, it was decided to study the strain rate effect on SEA using the type 1 series. From the experiments conducted, the SEA of each tube was calculated based on the higher deformation length of each series. From Fig. 21, it can be noted that the energy absorption of SP1 tube was sensitive to the impact velocity. There was a linear increase in SEA of 26% from the lower to the higher velocity. In the case of the CP series, there was a positive dependency with respect to the strain rate; however, the difference in SEA was small. Similarly, for the CV series there was no appreciable increase in SEA from 9.3 m/s to 12.4 m/s, in contrast a negative dependency was observed for 14 m/s.

The effect of resin type on SEA can be concluded from the comparison of CP and CV series. In all cases, the CV1 tubes absorbed more energy than CP1 series. This is clearly evident from the fact that the SEA of CV1 series is higher than CP1 series by 33% for initial impact velocities of 9.3 and 12.4 m/s. A difference of 27% was noted for the case of 14 m/s impact velocity. One reason for the increase in SEA could be the higher tensile strength and modulus of the vinylester which causes better interlaminar strength. Furthermore, due to the smaller diameter of CV tubes, more blockage of material (debris) occurred at the inner wall. This phenomenon also may be attributed to an increase in SEA.

4. Conclusions

In this study, the impact energy absorption characteristics and the crushing mechanism using glass fibre/polyester and glass fibre/vinylester square and circular tubes with different thicknesses were investigated. The different t/D ratio and linear densities were chosen to achieve progressive failure of the tubes. The effect of tube geometry, triggering, strain rate and the type of resin on the specific energy absorption was studied. From the experimental results obtained for three impact velocities it can be concluded that:

- In all cases, the circular tube was found to absorb more energy than the square tubes. For different impact velocities (9.3, 12.4 and 14 m/s), the circular tubes with t/D ratio of 0.06 yielded approximately 59%, 45% and 28% increase in SEA compared to the square tube with t/W ratio of 0.075. The increase in SEA of the circular tube was due to the geometry of the tube which
controls the deceleration of the impactor by progressive crushing.

- Out of the two types of triggering, the type 1 (45° chamfering around the edge of the tube) absorbed more energy than the type 2 (tulip pattern). In the case of circular tubes, due to triggering type 1, an increase in SEA of 7–9% was observed. The increase in SEA was explained by the uniform circumferential delamination followed by the axial cracks of the tubes. However, in the case of square tubes, there was a negative effect observed due to triggering type 1. The triggering type 2 showed 16.5% increase in SEA compared to triggering type 1. This is due to the fact that, in the case of square tubes, a significant amount of energy was absorbed by lamina bending followed by the shear fracture of the fibres. The lower laminate stiffness of triggering type 2 enhanced above said failure modes.

- The SEA of the square tube was found to be strain rate sensitive. A 26% increase in SEA was seen with increasing impact velocities. However, in the case of circular tubes (made with glass polyester and glass vinylester) there was no significant increase in SEA with increasing impact velocities.

- Finally, studies of the glass polyester and glass vinylester tubes showed that tubes made of glass vinylester absorbed more energy (SEA of 33–27%) than the glass–polyester tubes. The increase in SEA was due to the better interlaminar strength, higher strain to failure of vinylester resin and the blockage of inner material due to the smaller diameter of the tube.

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